

Document Number: MPC17529 Rev. 4.0, 10/2015

0.7 A Dual H-Bridge Motor Driver

# with 3.0 V/5.0 V Compatible Logic I/O

The 17529 is a monolithic dual H-Bridge power IC ideal for portable electronic applications containing bipolar step motors and/or brush DC-motors (e.g., cameras and disk drive head positioners).

The 17529 operates from 2.0 V to 6.8 V, with independent control of each H-Bridge via parallel MCU interface (3.0 V and 5.0 V compatible logic). The device features an on-board charge pump, as well as built-in shoot-through current protection and an undervoltage shutdown function.

The 17529 has four operating modes: forward, reverse, brake, and tri-stated (high-impedance). The 17529 has a low total R<sub>DS(on)</sub> of 1.2  $\Omega$  (max at 25 °C).

The 17529's low output resistance and high slew rate provides efficient drive for many types of micromotors.

#### **Features**

- Low total R<sub>DS(on)</sub> 0.7  $\Omega$  (typ), 1.2  $\Omega$  (max) at 25 °C
- Output current 0.7 A (DC), 1.4 A (peak)
- · Shoot-through current protection circuit
- 3.0 V/5.0 V CMOS-compatible inputs
- PWM control input frequency up to 200 kHz
- · Built-in charge pump circuit
- · Low power consumption
- · Undervoltage detection and shutdown circuit

17529

**DUAL H-BRIDGE** 







EJ SUFFIX (PB-FREE) 98ASA00887D 20-PIN TSSOP WITH EXPOSED PAD

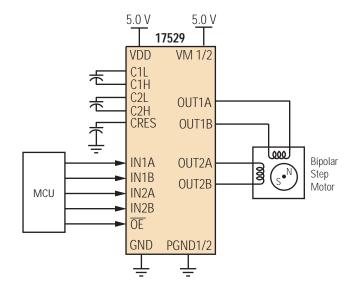


Figure 1. 17529 Simplified Application Diagram



# **ORDERABLE PARTS**

## Table 1. Orderable Part Variations (1)

Part Number	Temperature (T <sub>A</sub> )	Package
MPC17529EV/EL (2)	-20 °C to 65 °C	20 VMFP
MPC17529EJ	-20 0 10 03 0	20 TSSOP (exposed pad)

- 1. To order parts in Tape & Reel, add the R2 suffix to the part number.
- 2. Not recommended for new designs.



# **INTERNAL BLOCK DIAGRAM**

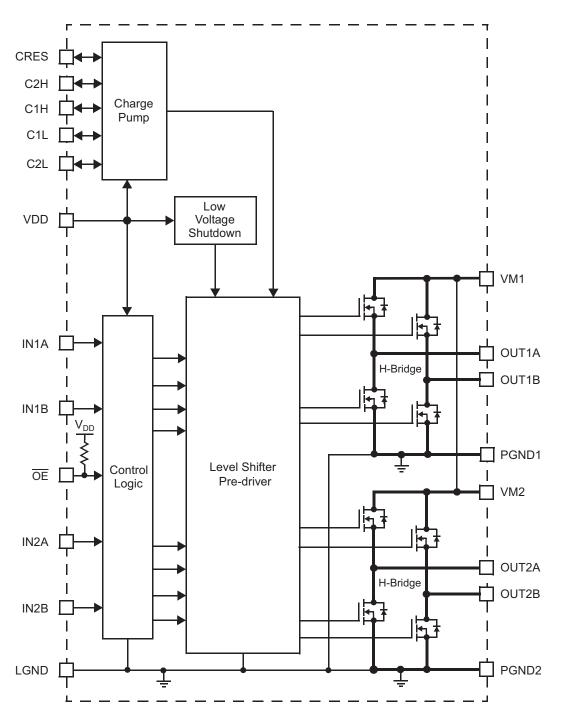


Figure 2. 17529 Simplified Internal Block Diagram



# **PIN CONNECTIONS**

Transparent top view

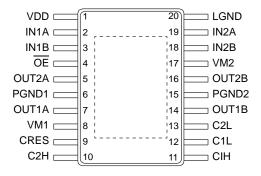


Figure 3. 17529 Pin Connections

on Table 2. Pin Function Description

Pin	PinName	Formal Name	Definition
1	VDD	Control Circuit Power Supply	Positive power source connection for control circuit.
2	IN1A	Logic Input Control 1A	Logic input control of OUT1A (refer to Table 6, Truth Table, page 8).
3	IN1B	Logic Input Control 1B	Logic input control of OUT1B (refer to Table 6, Truth Table, page 8).
4	ŌĒ	Output Enable	Logic output Enable control of H-Bridges (Low = True).
5	OUT2A	H-Bridge Output 2A	Output A of H-Bridge channel 2.
6	PGND1	Power Ground 1	High-current power ground 1.
7	OUT1A	H-Bridge Output 1A	Output A of H-Bridge channel 1.
8	VM1	Motor Drive Power Supply 1	Positive power source connection for H-Bridge 1 (Motor Drive Power Supply).
9	CRES	Pre-driver Power Supply	Internal triple charge pump output as pre-driver power supply.
10	C2H	Charge Pump 2H	Charge pump bucket capacitor 2 (positive pole).
11	C1H	Charge Pump 1H	Charge pump bucket capacitor 1 (positive pole).
12	C1L	Charge Pump 1L	Charge pump bucket capacitor 1 (negative pole).
13	C2L	Charge Pump 2L	Charge pump bucket capacitor 2 (negative pole).
14	OUT1B	H-Bridge Output 1B	Output B of H-Bridge channel 1.
15	PGND2	Power Ground 2	High-current power ground 2.
16	OUT2B	H-Bridge Output 2B	Output B of H-Bridge channel 2.
17	VM2	Motor Drive Power Supply 2	Positive power source connection for H-Bridge 2 (Motor Drive Power Supply).
18	IN2B	Logic Input Control 2B	Logic input control of OUT2B (refer to Table 6. Truth Table, page 8).
19	IN2A	Logic Input Control 2A	Logic input control of OUT2A (refer to Table 6. Truth Table, page 8).
20	LGND	Logic Ground	Low-current logic signal ground.
-	-	-	Exposed pad on 20-Pin TSSOP



## **MAXIMUM RATINGS**

## **Table 3. Maximum Ratings**

All voltages are with respect to ground unless otherwise noted. Exceeding the ratings may cause a malfunction or permanent damage to the device.

Symbol	Rating	Value	Unit	Notes
V <sub>M</sub>	Motor Supply Voltage	-0.5 to 8.0	V	
V <sub>CRES</sub>	Charge Pump Output Voltage	-0.5 to 14	V	
$V_{DD}$	Logic Supply Voltage	-0.5 to 7.0	V	
V <sub>IN</sub>	Signal Input Voltage	-0.5 to V <sub>DD</sub> +0.5	V	
I <sub>O</sub> I <sub>OPK</sub>	Driver Output Current	0.7 1.4	А	(3)
V <sub>ESD1</sub> V <sub>ESD2</sub>	ESD Voltage • Human Body Model • Machine Model	±1500 ±200	V	(4) (5)
TJ	Operating Junction Temperature	-20 to 150	°C	
T <sub>A</sub>	Operating Ambient Temperature	-20 to 65	°C	
T <sub>STG</sub>	Storage Temperature Range	-65 to 150	°C	
$R_{\theta JA}$	Thermal Resistance	120	°C/W	(6)
P <sub>D</sub>	Power Dissipation	1040	mW	(7)
T <sub>PPRT</sub>	Peak Package Reflow Temperature During Reflow	Note 9	°C	(8), (9)

- 3.  $T_A = 25$  °C, 10 ms pulse at 200 ms interval.
- 4. ESD1 testing is performed in accordance with the Human Body Model ( $C_{ZAP} = 100 \text{ pF}, R_{ZAP} = 1500 \Omega$ ).
- 5. ESD2 testing is performed in accordance with the Machine Model ( $C_{ZAP} = 200 \text{ pF}$ ,  $R_{ZAP} = 0 \Omega$ ).
- 6. Mounted on 37 x 50 Cu area (1.6 mm FR-4 PCB).
- 7.  $T_A = 25 \, ^{\circ}C$ .
- 8. Pin soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause a malfunction or permanent damage to the device.
- 9. Freescale's Package Reflow capability meets Pb-free requirements for JEDEC standard J-STD-020C. For Peak Package Reflow Temperature and Moisture Sensitivity Levels (MSL), Go to www.freescale.com, search by part number [e.g. remove prefixes/suffixes and enter the core ID to view all orderable parts (i.e. MC33xxxD enter 33xxx), and review parametrics.



## STATIC ELECTRICAL CHARACTERISTICS

## **Table 4. Static Electrical Characteristics**

Characteristics noted under conditions  $T_A = 25$  °C,  $V_{DD} = V_M = 5.0$  V, GND = 0 V, unless otherwise noted.

Symbol	Characteristic	Min	Тур	Max	Unit	Notes
OWER (VM1, V	M2, VDD)					I
V <sub>M</sub>	Motor Supply Voltage	2.0	5.0	6.8	V	
V <sub>DD</sub>	Logic Supply Voltage	2.7	5.0	5.6	V	
I <sub>QM</sub>	Driver Quiescent Supply Current (No Signal Input)	-	-	1.0	μΑ	
I <sub>QVDD</sub>	Logic Quiescent Supply Current (No Signal Input) (10)	-	-	1.0	mA	
I <sub>DVDD</sub> I <sub>CRES</sub>	Operating Power Supply Current  • Logic Supply Current (11)  • Charge Pump Circuit Supply Current (12)		- -	3.0 0.7	mA	
V <sub>DDDET</sub>	Low V <sub>DD</sub> Detection Voltage <sup>(13)</sup>	1.5	2.0	2.5	V	
R <sub>DS(ON)</sub>	Driver Output ON Resistance (14)	-	0.7	1.2	Ohms	
ATE DRIVE (C	IL-C1H, C2L-C2H, CRES)					· I
V <sub>CRES</sub>	Gate Drive Voltage	12	13	13.5	V	
C <sub>CP</sub>	Recommended External Capacitance (C1L-C1H, C2L-C2H, C <sub>RES</sub> -GND)	0.01	0.1	1.0	μF	
ONTROL LOGI	C (OE, N1A, N1B, N2A, N2B)					
V <sub>IN</sub>	Logic Input Voltage	0.0	-	$V_{DD}$	V	
V <sub>IH</sub> V <sub>IL</sub> I <sub>IH</sub>	Logic Inputs (2.7 V < V <sub>DD</sub> < 5.7 V)  • High-Level Input Voltage  • Low-Level Input Voltage  • High-Level Input Current	V <sub>DD</sub> x 0.7	- - -	- V <sub>DD</sub> x 0.3 1.0	V V μΑ	
I <sub>IL</sub> I <sub>OILOE</sub>	<ul> <li>Low-Level Input Current</li> <li>OE Pin Input Current Low</li> </ul>	-1.0 -	- 50	- 100	μA μA	

- 10.  $I_{QVDD}$  includes the current to pre-driver circuit.
- 11.  $I_{VDD}$  includes the current to pre-driver circuit at  $f_{IN} = 100$  kHz.
- 12. At  $f_{IN} = 20 \text{ kHz}$ .
- 13. Detection voltage is defined as when the output becomes high-impedance after  $V_{DD}$  drops below the detection threshold. When the gate voltage  $V_{CRES}$  is applied from an external source,  $V_{CRES} = 7.5 \text{ V}$ .
- 14. Source+sink at  $I_0 = 0.7 A$ .



# **DYNAMIC ELECTRICAL CHARACTERISTICS**

# **Table 5. Dynamic Electrical Characteristics**

Characteristics noted under conditions  $T_A = 25$  °C,  $V_{DD} = V_M = 5.0$  V, GND = 0 V, unless otherwise noted.

Symbol	Characteristic	Min	Тур	Max	Unit	
NPUT (IN1A, IN1	B, OE, IN2A, IN2B)					
f <sub>IN</sub>	Pulse Input Frequency	-	-	200	kHz	
t <sub>R</sub>	Input Pulse Rise Time	_	_	1.0 <sup>(16)</sup>	μs	(15)
t <sub>F</sub>	Input Pulse Fall Time	-	_	1.0 <sup>(16)</sup>	μs	(17)
OUTPUT (OUT1A	A, OUT1B, OUT2A, OUT2B)					
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay Time • Turn-ON Time • Turn-OFF Time	- -	0.1 0.1	0.5 0.5	μs	(18)
t <sub>VGON</sub>	Charge Pump Wake-Up Time	-	1.0	3.0	ms	(19)
t <sub>VDDDET</sub>	Low-Voltage Detection Time	_	_	10	ms	

- 15. Time is defined between 10% and 90%.
- 16. That is, the input waveform slope must be steeper than this.
- 17. Time is defined between 90% and 10%.
- 18. Load of Output is 8.0  $\Omega$  resistance.
- 19.  $C_{CP} = 0.1 \,\mu\text{F}.$



# **TIMING DIAGRAMS**

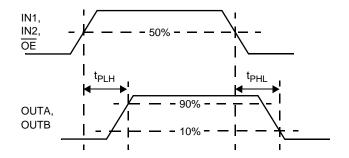


Figure 4.  $t_{PLH}$ ,  $t_{PHL}$ , and  $t_{PZH}$  Timing

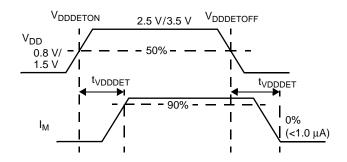


Figure 5. Low-Voltage Detection Timing Diagram

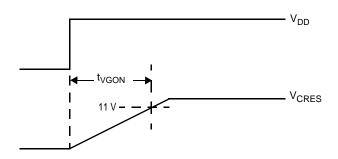


Figure 6. Charge Pump Timing Diagram

Table 6. Truth Table

INPUT			ОИТ	PUT
ŌĒ	IN1A IN2A	IN1B IN2B	OUT1A OUT2A	OUT1B OUT2B
L	L	L	L	L
L	Н	L	Н	L
L	L	Н	L	Н
L	Н	Н	Z	Z
Н	X	Х	Z	Z

H = High.

L = Low. Z = High-impedance.

 $\frac{X}{OE}$  = Don't care.  $\frac{X}{OE}$  Pin is pulled up to  $V_{DD}$  with internal resistance.



## SYSTEM/APPLICATION INFORMATION

#### INTRODUCTION

The 17529 is a monolithic dual H-Bridge ideal for portable electronic applications to control bipolar step motors and brush DC motors, such as those found in camera lens assemblies, camera shutters, optical disk drives, etc. The 17529 operates from 2.0 V to 6.8 V, providing dual H-bridge motor drivers with parallel 3.0 V or 5.0 V compatible I/O. The device features an on-board charge pump, as well as built-in shoot-through current protection and undervoltage shutdown.

The 17529 has four operating modes: forward, reverse, brake, and tri-stated (high-impedance). The MOSFETs comprising the output bridge have a total source + sink  $R_{DS(ON)} \le 1.2~\Omega$ . The 17529 can simultaneously drive two brush DC motors or, as shown in Figure 1, 17529 Simplified Application Diagram on page 1, one bipolar step motor. The drivers are designed to be PWM'ed at frequencies up to 200 kHz.

#### **FUNCTIONAL PIN DESCRIPTION**

## **CONTROL CIRCUIT POWER SUPPLY (VDD)**

The VDD pin carries the logic supply voltage and current into the logic sections of the IC. VDD has an undervoltage threshold. If the supply voltage drops below the undervoltage threshold, the output power stage switches to a tri-state condition. When the supply voltage returns to a level that is above the threshold, the power stage automatically resumes normal operation according to the established condition of the input pins.

#### LOGIC INPUT CONTROL (IN1A, IN1B, IN2A, AND IN2B)

These logic input pins control each H-Bridge output. IN1A logic HIGH = OUT1A HIGH. However, if all inputs are taken HIGH, the outputs bridges are both tri-stated (refer to Table 6, Truth Table, page 8).

#### **OUTPUT ENABLE (OE)**

The  $\overline{OE}$  pin is a LOW = TRUE enable input. When  $\overline{OE}$  = HIGH, all H-Bridge outputs (OUT1A, OUT1B, OUT2A, and OUT2B) are tristated (high-impedance), regardless of logic input (IN1A, IN1B, IN2A, and IN2B) states.

#### H-BRIDGE OUTPUT (OUT1A, OUT1B, OUT2A, AND OUT2B)

These pins provide connection to the outputs of each of the internal H-Bridges (see <u>Figure 2, 17529 Simplified Internal Block Diagram</u>, page 3).

## MOTOR DRIVE POWER SUPPLY (VM1 AND VM2)

The VM pins carry the main supply voltage and current into the power sections of the IC. This supply then becomes controlled and/or modulated by the IC as it delivers the power to the loads attached between the output pins. All VM pins must be connected together on the printed circuit board.

## CHARGE PUMP (C1L AND C1H, C2L AND C2H)

These two pairs of pins, the C1L and C1H and the C2L and C2H, connect to the external bucket capacitors required by the internal charge pump. The typical value for the bucket capacitors is 0.1 µF.

## PRE-DRIVER POWER SUPPLY (CRES)

The CRES pin is the output of the internal charge pump. Its output voltage is approximately three times the  $V_{DD}$  voltage. The  $V_{CRES}$  voltage is power supply for internal pre-driver circuit of H-Bridges.

#### **POWER GROUND (PGND)**

Power ground pins. They must be tied together on the PCB.

#### LOGIC GROUND (LGND)

Logic ground pin.



#### **APPLICATIONS**

#### TYPICAL APPLICATION

Figure 7 shows a typical application for the 17529. When applying the gate voltage to the CRES pin from an external source, be sure to connect it via a resistor equal to, or greater than,  $R_G = V_{CRES}/0.02 \Omega$ .

The internal charge pump of this device is generated from the VDD supply; therefore, care must be taken to provide sufficient gate-source voltage for the high side MOSFETs when  $V_M >> V_{DD}$  (e.g.,  $V_M = 5.0 \text{ V}$ ,  $V_{DD} = 3.0 \text{ V}$ ), in order to ensure full enhancement of the high-side MOSFET channels.

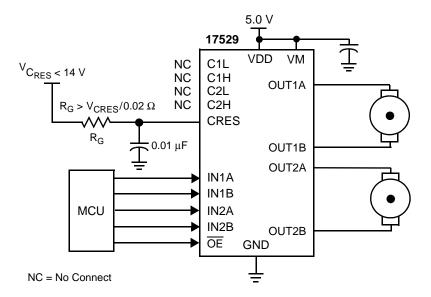


Figure 7. 17529 Typical Application Diagram

## CONDUCTED ELECTROMOTIVE FORCE (CEMF) SNUBBING TECHNIQUES

Care must be taken to protect the IC from potentially damaging CEMF spikes induced when commutating currents in inductive loads. Typical practice is to provide snubbing of voltage transients by placing a capacitor or zener at the supply pin (VM) (see Figure 8).

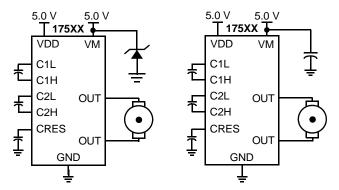


Figure 8. CEMF Snubbing Techniques

## **PCB LAYOUT**

When designing the printed circuit board (PCB), connect sufficient capacitance between power supply and ground pins to ensure proper filtering from transients. For all high-current paths, use wide copper traces and shortest possible distances.



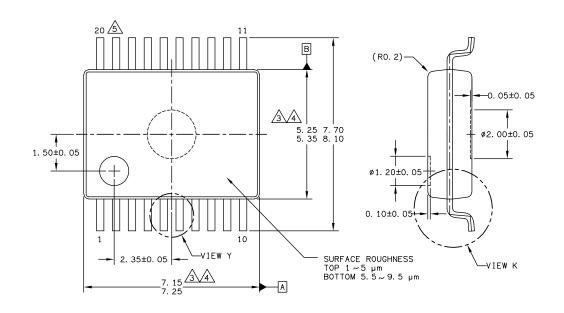
# **PACKAGE DIMENSIONS**

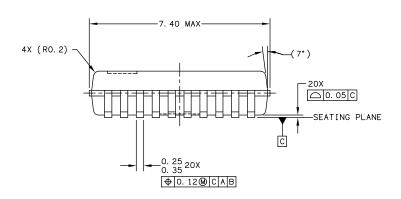
Package dimensions are provided in package drawings. To find the most current package outline drawing, go to <a href="https://www.freescale.com">www.freescale.com</a> and perform a keyword search for the drawing's document number.

## Table 7.

Package	Suffix	Package Outline Drawing Number
20-PIN VMFP	EV	98ASA10616D
20-TSSOP	EJ	98ASA00887D

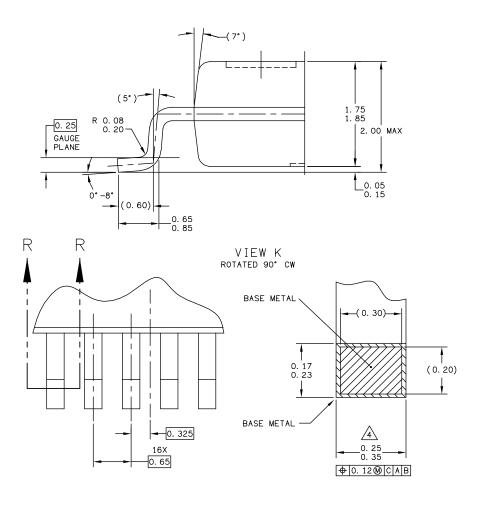






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EIAJ VMFP 20 0 65 PITCH	' LCASE NUME	BER: 1569-02	01 DEC 2006
	'	NON-JEDEC	





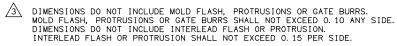
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		STANDARD: NO	N-JEDEC	



#### NOTES:

- 1 DIMENSIONING AND TOLERANCING PER ASME Y14.5M 1994.
- 2 ALL DIMENSIONS ARE IN MILLIMETERS.

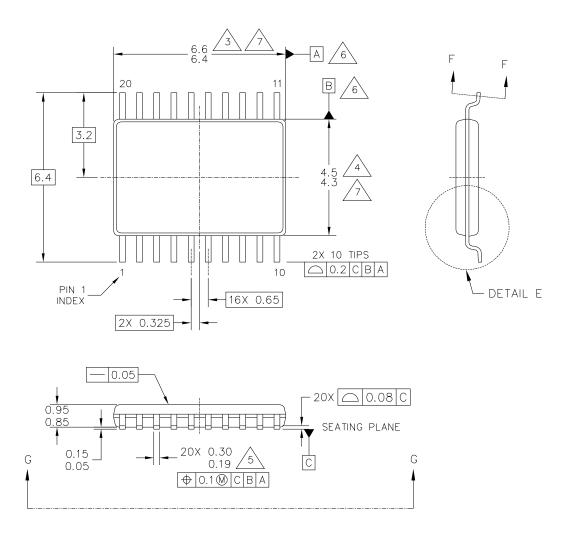


DIMENSIONS ARE DETERMINED AT THE OUTMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS, AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.

TERMINAL NUMBER ARE SHOWN FOR REFERENCE ONLY.

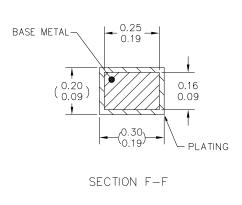
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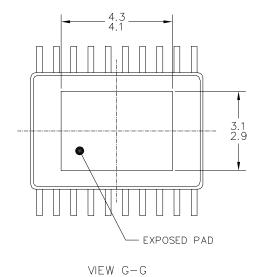


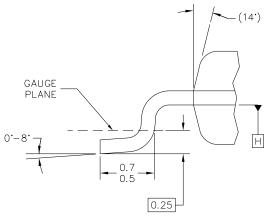


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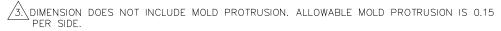
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#### NOTES:

- 1. DIMENSIONS AND TOLERANCING PER ASME Y14.5M-1994.
- 2. DIMENSIONS ARE IN MILLIMETERS.



DIMENSION DOES NOT INCLUDE INTERLEAD FLASH OR MOLD PROTRUSION. INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.25 PER SIDE.

DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE MAXIMUM DIMENSION BY MORE THAN 0.08 MM. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD OR PROTRUSION 0.07 MM.

6. Datums a and b to be determined at datum plane H. 7. Dimensions to be determined at seating plane C.

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# **REVISION HISTORY**

Revision	Date	Description of Changes	
2.0	9/2005	<ul><li>Implemented Revision History page</li><li>Converted to Freescale format</li></ul>	
	12/2013	<ul> <li>No technical changes</li> <li>Revised back page</li> <li>Updated document properties</li> </ul>	
3.0	7/2015	<ul> <li>Added 98ASA00887D package information and updated tables where applicable</li> <li>Added MPC17529EJ to the ordering information</li> <li>Updated as per PCN # 16724</li> </ul>	
	8/2015	Corrected the 98A package information for 20-pin TSSOP	
4.0	10/2015	<ul> <li>Added EP notation for TSSOP package.</li> <li>Fixed notations for TSSOP in Orderable Parts and Pin Connections.</li> <li>Updated Package Dimensions 98A drawing for TSSOP</li> </ul>	





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